

**IN THE SPECIFICATION:**

Please amend paragraph [0023] of the specification *as published* as follows:

[0023] The FIGURE shows by way of example a traffic scene using the method according to the invention in order to sense the surroundings in front of a road vehicle (1) by means of a surroundings sensing system. In which case the road vehicle is located on a road with a plurality of lanes (2). The boundaries (6) of the region imaged by the surroundings sensing camera extend beyond the lane boundaries (3). The perception region of the system is intended to include here only a component-region of the region which can be imaged by the camera. The perception region is also intended to be divided into a plurality of component-regions (A . . . D) in order to subject the surroundings data to a multi-stage evaluation. The perception region is restricted in this example to the region which is located within the lane boundaries (3). Also, a further tolerance region (5) is added in addition to the perception ~~preception~~ region in order, for example, to perceive road signs in this region. If the central markings (4) are also included, up to four perception component-regions (C1 . . . C4) are produced one next to the other, for example, when there are two lanes (2) as indicated in the figure. Correspondingly it is conceivable for the number of perception component-regions which are located one next to the other to increase with the number of lanes (2).